



HUMAN-COMPUTER INTERACTION THIRD EDITION DIX FINLAY ABOUDD BEALE

chapter 15

task models

extract for MSc/MRes AISD



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What is Task Analysis?

Methods to analyse people's jobs:

- what people do
- what things they work with
- what they must know



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An Example

- in order to clean the house
 - get the vacuum cleaner out
 - fix the appropriate attachments
 - clean the rooms
 - when the dust bag gets full, empty it
 - put the vacuum cleaner and tools away
- must know about:
 - vacuum cleaners, their attachments, dust bags, cupboards, rooms etc.



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Approaches to task analysis

- Task decomposition
 - splitting task into (ordered) subtasks
- Knowledge based techniques
 - what the user knows about the task and how it is organised
- Entity/object based analysis
 - relationships between objects, actions and the people who perform them
- lots of different notations/techniques



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general method

- observe
- collect unstructured lists of words and actions
- organize using notation or diagrams



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Differences from other techniques

Systems analysis	vs.	Task analysis
system design	- focus -	the user
Cognitive models	vs.	Task analysis
internal mental state	- focus -	external actions
practiced 'unit' task	- focus -	whole job

Task Decomposition

Aims:

describe the actions people do
structure them within task subtask hierarchy
describe order of subtasks

Variants:

Hierarchical Task Analysis (HTA)
most common
CTT (CNUCE, Pisa)
uses LOTOS temporal operators

Textual HTA description

Hierarchy description ...

0. in order to clean the house
 1. get the vacuum cleaner out
 2. get the appropriate attachment
 3. clean the rooms
 - 3.1. clean the hall
 - 3.2. clean the living rooms
 - 3.3. clean the bedrooms
 4. empty the dust bag
 5. put vacuum cleaner and attachments away
- ... and plans
Plan 0: do 1 - 2 - 3 - 5 in that order. when the dust bag gets full do 4
Plan 3: do any of 3.1, 3.2 or 3.3 in any order depending on which rooms need cleaning

N.B. only the plans denote order

Generating the hierarchy

- 1 get list of tasks
- 2 group tasks into higher level tasks
- 3 decompose lowest level tasks further

Stopping rules

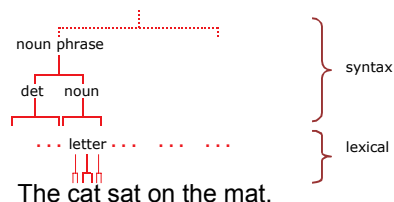
How do we know when to stop?
Is "empty the dust bag" simple enough?
Purpose: expand only relevant tasks
Motor actions: lowest sensible level

Tasks as explanation

- imagine asking the user the question:
what are you doing now?
- for the same action the answer may be:
typing ctrl-B
making a word bold
emphasising a word
editing a document
writing a letter
preparing a legal case

HTA as grammar

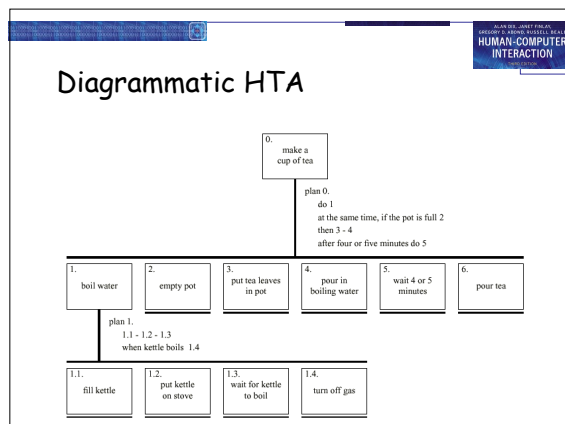
- can parse sentence into letters, nouns, noun phrase, etc.



parse scenario using HTA

- | | | | |
|--------------------|------|---|----|
| get out cleaner | 1. | } | 0. |
| fix carpet head | 2. | | |
| clean dinning room | 3.2. | | |
| clean main bedroom | 3.3. | | |
| empty dustbag | 4. | | |
| clean sitting room | 3.2. | } | 5. |
| put cleaner away | | | |

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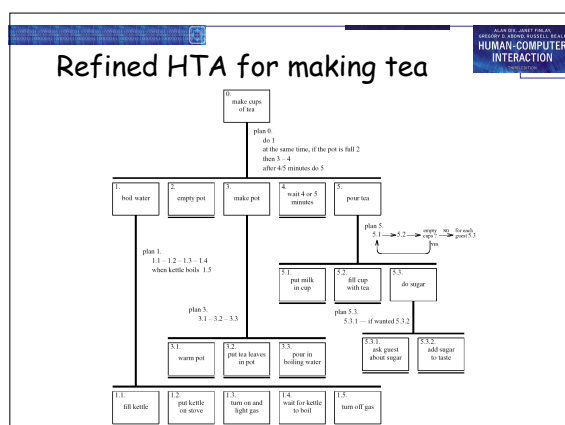


Refining the description

Given initial HTA (textual or diagram)
How to check / improve it?

Some heuristics:

- paired actions e.g., where is 'turn on gas'
- restructure e.g., generate task 'make pot'
- balance e.g., is 'pour tea' simpler than making pot?
- generalise e.g., make one cup or more



Types of plan

- fixed sequence - 1.1 then 1.2 then 1.3
- optional tasks - if the pot is full 2
- wait for events - when kettle boils 1.4
- cycles - do 5.1 5.2 while there are still empty cups
- time-sharing - do 1; at the same time ...
- discretionary - do any of 3.1, 3.2 or 3.3 in any order
- mixtures - most plans involve several of the above

waiting ...

- is waiting part of a plan?
... or a task?
- generally
 - task - if 'busy' wait
 - you are actively waiting
 - plan - if end of delay is the event
 - e.g. "when alarm rings", "when reply arrives"
- in this example ...
 - perhaps a little redundant ...
 - TA not an exact science

see chapter 19 for more on delays!